CS 43: Computer Networks
Structure, Threading, and Blocking

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Announcements
Agenda

• Under-the-hood look at networking system calls
  • Data buffering and blocking

• Processes, threads, and concurrency models

• Event-based, non-blocking I/O
Motivation: What is the goal of a network?

• Allow devices communicate with one another and coordinate their actions to work together.

(This was a slide from day 1)
Recall Inter-process Communication (IPC)

• Processes must communicate to cooperate

• Must have two mechanisms:
  • Data transfer
  • Synchronization
Inter-process Communication (IPC)

• Operating systems provide several IPC mechanisms (Take CS 45)
  • files
  • shared memory (in several ways)
  • pipes
  • ...
  • sockets

• Broadly, these fall into two categories:
  1. Shared memory
  2. Message passing

Only works on one computer (shared hardware).
Also, this is what you’re most familiar with.
Thread Model (Shared Memory)

• Single process with multiple copies of execution resources.

• ONE shared virtual address space!
  • All process memory shared by every thread.
  • Threads coordinate by sharing variables (typically on heap)

Note: this is technically not IPC (there's only one process), but this is the most common form of shared memory today.
Let's say process $P_1$ wants to send data to process $P_2$.

They execute on the same hardware and share an operating system.

They do NOT directly share any memory.
Message Passing IPC (Pipe)

P₁ can send data into the pipe by calling:

\[ \text{write}(\ldots, \text{data pointer}, \text{count}) \]

data pointer: the start of data to copy

count: how many bytes to copy (at most)
Message Passing IPC (Pipe)

P₁ can send data into the pipe by calling:

\[ \text{write}(\ldots, \text{data pointer}, \text{count}) \]

data pointer: the start of data to copy

NAME

write - write to a file descriptor

SYNOPSIS

\[ \text{#include <unistd.h>} \]

\[ \text{ssize_t write(int } \text{fd, const void *buf, size_t count);} \]

DESCRIPTION

write() writes up to \text{count} bytes from the buffer starting at \text{buf} to the file referred to by the file descriptor \text{fd}. 
Message Passing IPC (Pipe)

P₁ can send data into the pipe by calling:

\[ \text{write(fd, data pointer, count)} \]

data pointer: the start of data to copy

count: how many bytes to copy
P₁ can send data into the pipe by calling:

\texttt{write(\ldots, data\ motivated, count)}

data pointer: the start of data to copy

count: how many bytes to copy (at most)
Message Passing IPC (Pipe)

P₂ can receive data from the pipe by calling:

`read(…, data pointer, count)`

data pointer: the start of location to copy into

count: how many bytes to copy (at most)
**Message Passing IPC (Pipe)**

P₂ can receive data from the pipe by calling:

`read(...)`, `data pointer`, `count`

- `data pointer`: the start of location to copy into
- `count`: how many bytes to copy (at most)
Message Passing IPC (Pipe)

Data transfer: data moves in (write) and out (read) of OS message buffer

Synchronization: ?
Where is the synchronization* in message passing IPC? (*application synchronization)

A. The OS adds synchronization.

B. Synchronization is determined by the order of sends and receives.

C. The communicating processes exchange synchronization messages (lock/unlock).

D. There is no synchronization mechanism.
Message Passing IPC (Socket)

Let's say process $P_1$ wants to send data to process $P_2$. They execute on the different hardware and share nothing but a network connection.
Message Passing IPC (Socket)

P₁ can send data into the socket by calling:

```
send(…, data pointer, count, …)
```

data pointer: the start of data to copy

count: how many bytes to copy (at most)
P₁ can send data into the socket by calling:

```c
send(..., data pointer, count, ...
```

data pointer: the start of data to copy

count: how many bytes to copy (at most)

NAME

send, sendto, sendmsg — send a message on a socket

SYNOPSIS

```c
#include <sys/types.h>
#include <sys/socket.h>

ssize_t send(int sockfd, const void *buf, size_t len, int flags);
```
Message Passing IPC (Socket)

NAME
write - write to a file descriptor

SYNOPSIS
#include <unistd.h>

ssize_t write(int fd, const void *buf, size_t count);

DESCRIPTION
write() writes up to count bytes from the buffer starting at buf to
the file referred to by the file descriptor fd.

NAME
send, sendto, sendmsg - send a message on a socket

SYNOPSIS
#include <sys/types.h>
#include <sys/socket.h>

ssize_t send(int sockfd, const void *buf, size_t len, int flags);
Message Passing IPC (Socket)

$P_1$ can send data into the socket by calling:

```
send(..., data pointer, count, ...)
```

data pointer: the start of data to copy

count: how many bytes to copy (at most)
Message Passing IPC (Socket)

The sender's OS will transmit the data to the receiver's OS when it's convenient to do so.
Message Passing IPC (Socket)

P₂ can receive data from the pipe by calling:
`recv(..., data pointer, count, ...)`

data pointer: the start of location to copy into

count: how many bytes to copy (at most)
Questions about this model?

Don't worry about "how many" bytes yet.
Questions about this model?

Don't worry about "how many" bytes yet.

"Socket buffer"
• OS stores a table, per process, of descriptors
Descriptors

Where do descriptors come from?

What are they?

```
int open(const char *pathname, int flags);  
int open(const char *pathname, int flags, mode_t mode)
```

```
#include <sys/types.h>  
#include <sys/socket.h>  

int socket(int domain, int type, int protocol);
```
OS stores a table, per process, of descriptors
socket()

- socket() returns a socket descriptor
- Indexes into table

```c
int sock = socket(AF_INET, SOCK_STREAM, 0);
```

Table:

<table>
<thead>
<tr>
<th>0</th>
<th>1</th>
<th>2</th>
<th>...</th>
<th>7</th>
</tr>
</thead>
<tbody>
<tr>
<td>stdin</td>
<td>stdout</td>
<td>stderr</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Kernel
The function `socket()` is used to create a socket. The example shown is:

```c
int sock = socket(AF_INET, SOCK_STREAM, 0);
```

This creates a socket with the specified family (AF_INET), type (SOCK_STREAM), and protocol (0).

The OS stores details of the socket, connection, and pointers to buffers. The diagram illustrates the process and kernel interactions, showing how the sockets are managed. The socket details include:

- **Family**: AF_INET
- **Type**: SOCK_STREAM
- **Local address**: NULL
- **Local port**: NULL

Send buffer is not specified, and receive buffer is NULL.
socket()

- OS stores details of the socket, connection, and pointers to buffers

```c
int sock = socket(AF_INET, SOCK_STREAM, 0);
```

<table>
<thead>
<tr>
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<th>...</th>
<th>7</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>stdin</td>
<td>stdout</td>
<td>stderr</td>
<td></td>
</tr>
</tbody>
</table>

Family: AF_INET, Type: SOCK_STREAM
Local address: NULL, Local port: NULL
Send buffer, Receive buffer

Buffer: Temporary data storage location
Socket Buffers

int sock = socket(AF_INET, SOCK_STREAM, 0);

Process

Application buffer / storage space:

Operating System

Family: AF_INET, Type: SOCK_STREAM
Local address: NULL, Local port: NULL
Send buffer , Receive buffer
int sock = socket(AF_INET, SOCK_STREAM, 0);

Family: AF_INET, Type: SOCK_STREAM
Local address: NULL, Local port: NULL
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Application buffer / storage space:
Socket Buffers

Process

```c
int sock = socket(AF_INET, SOCK_STREAM, 0);
```

Application buffer / storage space:

Family: AF_INET, Type: SOCK_STREAM
Local address: NULL, Local port: NULL
Send buffer , Receive buffer

recv(): Move data from socket buffer to process.

Operating System

Internet
Socket Buffers

Process

```c
int sock = socket(AF_INET, SOCK_STREAM, 0);
```

Application buffer / storage space:

Family: AF_INET, Type: SOCK_STREAM
Local address: NULL, Local port: NULL
Send buffer 🟢, Receive buffer 💲

send(): Move data from process to socket buffer

Operating System

Internet
Socket Buffers

Process

```
int sock = socket(AF_INET, SOCK_STREAM, 0);
```

Application buffer / storage space:

```
+-----------------+----------+----------+
|                 |          |          |
|                 |          |          |
|                 |          |          |
|                 |          |          |
+-----------------+----------+----------+
```

Operating System

Family: AF_INET, Type: SOCK_STREAM
Local address: NULL, Local port: NULL
Send buffer , Receive buffer

Free space? Is data here?

Challenge: Your process does NOT know what is stored here!
recv()

Process

```c
int sock = socket(AF_INET, SOCK_STREAM, 0);
(assume we connect()ed here…)
int recv_val = recv(sock, r_buf, 200, 0);
```

Kernel

<table>
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<th>0</th>
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<th>...</th>
<th>7</th>
</tr>
</thead>
</table>

Family: AF_INET, Type: SOCK_STREAM
Local address: ..., Local port: ...
Send buffer [ ], Receive buffer [ ]

Is data here?
What should we do if the receive socket buffer is empty? If it has 100 bytes?

Process

```c
int sock = socket(AF_INET, SOCK_STREAM, 0);
(assume we connect()ed here...)
int recv_val = recv(sock, r_buf, 200, 0);
```

Two Scenarios:

- **Socket buffer (receive)**
  - Empty
  - 100 bytes

- **r_buf (size 200)**
What should we do if the receive socket buffer is empty? If it has 100 bytes?

Process

```
int sock = socket(AF_INET, SOCK_STREAM, 0);
(assume we connect()ed here…)
int recv_val = recv(sock, r_buf, 200, 0);
```

Two Scenarios:

<table>
<thead>
<tr>
<th></th>
<th>Empty</th>
<th>100 Bytes</th>
</tr>
</thead>
<tbody>
<tr>
<td>A</td>
<td>Block</td>
<td>Block</td>
</tr>
<tr>
<td>B</td>
<td>Block</td>
<td>Copy 100 bytes</td>
</tr>
<tr>
<td>C</td>
<td>Copy 0 bytes</td>
<td>Block</td>
</tr>
<tr>
<td>D</td>
<td>Copy 0 bytes</td>
<td>Copy 100 bytes</td>
</tr>
<tr>
<td>E</td>
<td>Something else</td>
<td></td>
</tr>
</tbody>
</table>

"Block" means pause the calling process.
What should we do if the send socket buffer is full? If it has 100 bytes?

**Process**

```c
int sock = socket(AF_INET, SOCK_STREAM, 0);
(assume we connect()ed here...)
int send_val = send(sock, s_buf, 200, 0);
```

**Two Scenarios:**

- **Socket buffer (send)**
  - Full
  - 100 bytes

- **Kernel**
What should we do if the send socket buffer is full? If it has 100 bytes?

Process

```c
int sock = socket(AF_INET, SOCK_STREAM, 0);  // (assume we connect()ed here...)
int send_val = send(sock, s_buf, 200, 0);
```

Two Scenarios:

<table>
<thead>
<tr>
<th></th>
<th>Full</th>
<th>100 Bytes</th>
</tr>
</thead>
<tbody>
<tr>
<td>A</td>
<td>Return 0</td>
<td>Copy 100 bytes</td>
</tr>
<tr>
<td>B</td>
<td>Block</td>
<td>Copy 100 bytes</td>
</tr>
<tr>
<td>C</td>
<td>Return 0</td>
<td>Block</td>
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<tr>
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<td>Block</td>
<td>Block</td>
</tr>
<tr>
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Socket buffer (send)

Full

100 bytes

Kernel
Blocking Implications

• DO NOT assume that you will recv() all of the bytes that you ask for.
• DO NOT assume that you are done receiving.
• ALWAYS receive in a loop!*

• DO NOT assume that you will send() all of the data you ask the kernel to copy.
• Keep track of where you are in the data you want to send.
• ALWAYS send in a loop!*

* Unless you’re dealing with a single byte, which is rare.
ALWAYS check send() return value!

• When send() return value is less than the data size, **you are responsible for sending the rest**.

Data sent: 0
Data to send: 130

send(sock, data, 130, 0);
ALWAYS check send() return value!

• When send() return value is less than the data size, **you are responsible for sending the rest.**

Data sent: 0  
Data to send: 130

send(sock, data, 130, 0);

Data sent: 60  
Data to send: 130

Data:
ALWAYS check send() return value!

• When send() return value is less than the data size, **you are responsible for sending the rest.**

Data sent: 0  
Data to send: 130

send(sock, data, 130, 0);

Data sent: 60  
Data to send: 130

// Copy the 70 bytes starting from offset 60.  
send(sock, data + 60, 130 - 60, 0);
ALWAYS check send() return value!

• When send() return value is less than the data size, **you are responsible for sending the rest.**

```
Data sent: 0
Data to send: 130
send(sock, data, 130, 0);
```

```
Data sent: 60
Data to send: 130
// Copy the 70 bytes starting from offset 60.
send(sock, data + 60, 130 - 60, 0);
```

Repeat until all bytes are sent. (data_sent == data_to_send)
Blocking Summary

`send()`
• Blocks when socket buffer for sending is full
• Returns less than requested size when buffer cannot hold full size

`recv()`
• Blocks when socket buffer for receiving is empty
• Returns less than requested size when buffer has less than full size

Always check the return value!
Concurrency

• Think you’re the only one talking to that server?
Without Concurrency

• Think you’re the only one talking to that server?
Without Concurrency

• Think you’re the only one talking to that server?
Multiple Processes

Web Server

Server fork()s

Child process recv()s

Web Server

Server fork()s

Services the new client request

Client

Client
Processes/Threads vs. Parent
(More details in an OS class...)

**Spawned Process**
- Inherits descriptor table
- Does not share memory
  - New memory address space
- Scheduled independently
  - Separate execution context
  - Can block independently

**Spawned Thread**
- Shares descriptor table
- Shares memory
  - Uses parent’s address space
- Scheduled independently
  - Separate execution context
  - Can block independently
Processes/Threads vs. Parent
(More details in an OS class…)

Spawned Process
• Inherits descriptor table
• Does not share memory
  • New memory address space
• Scheduled independently
  • Separate execution context
  • Can block independently

Spawned Thread
• Shares descriptor table
• Shares memory
  • Uses parent’s address space
• Scheduled independently
  • Separate execution context
  • Can block independently

Often, we don’t need the extra isolation of a separate address space. Faster to skip creating it and share with parent – threading.
Threads & Sharing

• Global variables and static objects are shared
  • Stored in the static data segment, accessible by any thread

• Dynamic objects and other heap objects are shared
  • Allocated from heap with malloc/free or new/delete

• Local variables are not shared
  • Refer to data on the stack
  • Each thread has its own stack
  • Never pass/share/store a pointer to a local variable on another thread’s stack
Whether processes or threads...

• Several benefits
  • Modularizes code:
    • one piece accepts connections, another services them
  • Each can be scheduled on a separate CPU
  • Blocking I/O can be overlapped
Which benefit is the most critical?

A. Modular code/separation of concerns.

B. Multiple CPU/core parallelism.

C. I/O overlapping.

D. Some other benefit.
Whether processes or threads...

- Several benefits
  - Modularizes code:
    - one piece accepts connections, another services them
  - Each can be scheduled on a separate CPU
  - Blocking I/O can be overlapped

- Still not maximum efficiency...
  - Creating/destroying threads still takes time
  - Requires memory to store thread execution state
  - Lots of context switching overhead
Non-blocking I/O

• A socket can be put into "non blocking" mode
  • For a single call to send/recv, pass flag (MSG_DONTWAIT)
  • To apply to socket for all calls, use fcntl (file control)

```c
int sock, result, flags = 0;
sock = socket(AF_INET, SOCK_STREAM, 0);
result = fcntl(sock, F_SETFL, flags|O_NONBLOCK)

(always check result – 0 on success)
```
Non-blocking I/O

• With O_NONBLOCK set on a socket (or MSG_DONTWAIT flag)
  • No operations will block!

• On recv(), if socket buffer is empty:
  • returns -1, errno is EAGAIN or EWOULDBLOCK

• On send(), if socket buffer is full:
  • returns -1, errno is EAGAIN or EWOULDBLOCK
How about...

server_socket = socket(), bind(), listen()
connections = []

while (1) {
    new_connection = accept(server_socket)
    if new_connection != -1, add it to connections
    for connection in connections:
        recv(connection, ...) // Try to receive
        send(connection, ...) // Try to send, if needed
}
Will this work?

```python
server_socket = socket(), bind(), listen()
connections = []

while (1) {
    new_connection = accept(server_socket)
    if new_connection != -1, add it to connections
    for connection in connections:
        recv(connection, ...)  // Try to receive
        send(connection, ...)  // Try to send, if needed
}
```

A. Yes, this will work.  
B. No, this will execute too slowly.  
C. No, this will use too many resources.  
D. No, this will still block.
Event-based Concurrency

• Rather than checking over and over, let the OS tell us when data can be read/written

• Create set of FDs we want to read and write

• Tell system to block until at least one of those is ready for us to use. The OS worries about selecting which one(s).

select()
int main(void) {
    fd_set rfds;
    struct timeval tv;
    int retval;

    /* Watch stdin (fd 0) to see when it has input. */
    FD_ZERO(&rfds);
    FD_SET(0, &rfds);

    /* Wait up to five seconds. */
    tv.tv_sec = 5;
    tv.tv_usec = 0;

    retval = select(1, &rfds, NULL, NULL, &tv);
    /* Don't rely on the value of tv now! */

    if (retval == -1)
        perror("select()");
    else if (retval)
        printf("Data is available now.\n");
        /* FD_ISSET(0, &rfds) will be true. */
    else
        printf("No data within five seconds.\n");
}
Event-based Concurrency

• Rather than checking over and over, let the OS tell us when data can be read/written

• Tell system to block until at least one of those is ready for us to use. The OS worries about selecting which one(s).

• Only one process/thread (or one per core)
  • No time wasted on context switching
  • No memory overhead for many processes/threads
Concurrency, so far...

**Threads/Processes**
- Create a new process/thread each time a new connection arrives
- One thread per connection

**Event-based Concurrency**
- Add sockets to descriptor set, use `select` to wait until one of them can do something
- One thread in total
Other Concurrency Patterns

Work Queue model: (a.k.a boss/worker or master/worker)

- Create many threads once and reuse them.

Each worker can perform I/O and block independently of the other. Each worker can fail independently without stopping the system.
Other Concurrency Patterns

Work Queue model:
(a.k.a boss/worker or master/worker)

• More complex: each thread takes several connections and uses event-based concurrency to handle its subset

Each worker can perform I/O and block independently of the other. Each worker can fail independently without stopping the system.
Many Other Models!

- Staged Event-Driven Architecture (SEDA)
- Asymmetric Multi-Process Event-Driven (AMPED)
Summary

• A network enables communication between processes
  • Many ways to structure communication, most require shared memory
  • For networks, we use sockets, which allows OS to buffer data

• OS manages socket buffers on behalf of processes
  • Asking for an operation that can't be performed will block the process
    • e.g., recv() from empty buffer or send() to full buffer

• Because blocking pauses the caller, must carefully structure apps