CS 31: Intro to Systems C Programming L07-08: ISA Assembly

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THIS IS WHAT LEARNING LOGIC GATES FEELS LIKE



"If you can do logic gates in your head, please confirm you are not a replicant"

http://smbc-comics.com/comic/logic-gates

Reading Quiz

- Note the red border!
- 1 minute per question

Check your frequency:

- Iclicker2: frequency AA
- Iclicker+: green light next to selection

For new devices this should be okay, For used you may need to reset frequency

Reset:

- hold down power button until blue light flashes (2secs)
- Press the frequency code: AA vote status light will indicate success
- No talking, no laptops, phones during the quiz

Agenda

- Hardware basics
 - Machine memory models
 - Digital signals
 - Logic gates

Today

- How to directly interact with hardware
- Instruction set architecture (ISA)
 - Interface between programmer and CPU
 - Established instruction format (assembly lang)
- Assembly programming (x86_64)

Abstraction



Abstraction



CPU Game Plan

- <u>Fetch</u> instruction from memory
- <u>Decode</u> what the instruction is telling us to do
 - Tell the ALU what it should be doing
 - Find the correct operands
- **Execute** the instruction (arithmetic, etc.)
- <u>Store</u> the result

Machine Code

Binary (O's and 1's) Encoding of ISA Instructions

- some bits: encode the instruction (opcode bits)
- others encode operand(s)

(eg) 01001010 opcode operands 01 001 010 ADD %r1 %r2

 different bits fed through different CPU circuitry:



Hardware: Control, Storage, ALU circuitry





(Clock rate can be faster.)

How a computer runs a program:



- We know: How HW Executes Instructions:
- This Week: Instructions and ISA
 - Program Encoding: C code to assembly code
 - Learn IA32 Assembly programming





You can see the results of intermediate compilation steps using different gcc flags

executable binary

Executable code (a.out)

machine code instructions



Machine Code

Binary (O's and 1's) Encoding of ISA Instructions

- some bits: encode the instruction (opcode bits)
- others encode operand(s)

(eg) **01**001010 **opcode** operands

01 001 010

ADD %r1 %r2

 different bits fed through different CPU circuitry:



Assembly Code



What is "assembly"?

push %rbp mov %rsp, %rbp sub \$16, %rsp movl \$10, -8(%rbp) movl \$20, -4 (%rbp) movl -4 (%rbp), \$rax addl \$rax, -8(%rbp) movl -8(%rbp), %rax leave

Assembly is the "human readable" form of the instructions a machine can understand.

objdump -d a.out

Object / Executable / Machine Code

Assembly

push	%ebp
mov	%esp, %ebp
sub	\$16, %esp
movl	\$10, -8(%ebp)
movl	\$20, -4(%ebp)
movl	-4(%ebp), \$eax
addl	\$eax, -8(%ebp)
movl	-8(%ebp), %eax
leave	

Machine Code (Hexadecimal)

55 89 E5 83 EC 10 C7 45 F8 0A 00 00 00 C7 45 FC 14 00 00 00 8B 45 FC 01 45 F8 B8 45 F8 С9

Almost a 1-to-1 mapping to Machine Code Hides some details like num bytes in instructions

Object / Executable / Machine Code

Assembly

```
push %ebp
mov %esp, %ebp
sub $16, %esp
movl $10, -8(%ebp)
movl $20, -4(%ebp)
movl -4(%ebp), $eax
addl $eax, -8(%ebp)
movl -8(%ebp), %eax
leave
```

nt main() {	
int a = 10;	
int b = 20;	
a = a + b;	
return a;	



- ISA (or simply architecture): Interface between lowest software level and the hardware.
- Defines the language for controlling CPU state:
 - Defines a set of instructions and specifies their machine code format
 - Makes CPU resources (registers, flags) available to the programmer
 - Allows instructions to access main memory (potentially with limitations)
 - Provides control flow mechanisms (instructions to change what executes next)

The agreed-upon interface between all software that runs on the machine and the hardware that executes it.

	Application / Program						
		ο	Operating				
		Comp	oiler	System		Instruction Set	
CPU / Processor		ocessor	r I/O system		Architecture	Architecture	
	Digital Circuits					-	
		Logic Gates					

The agreed-upon interface between all software that runs on the machine and the hardware that executes it.



- ISA is Interface between CPU and Compiler:
 - Compiler translates program source code to machine code of a target ISA
 - (e.g.) C program → gcc → ISA machine code (0's and 1's)

ISA Examples

- Intel IA-32 (80x86)
- ARM
- MIPS
- PowerPC
- IBM Cell
- Motorola 68k

- Intel x86_64
- Intel IA-64 (Itanium)
- VAX
- SPARC
- Alpha
- IBM 360

Intel x86 Family

Intel i386 (1985)

- 12 MHz 40 MHz
- ~300,000 transistors
- Component size: 1.5 μm



Intel Core i9 9900k (2018)

- ~4,000 MHz
- ~7,000,000,000 transistors
- Component size: 14 nm



Everything in this family uses the same ISA (Same instructions)!

- ISA (or simply architecture): Interface between lowest software level and the hardware.
- Defines the language for controlling CPU state:
 - Defines a set of instructions and specifies their machine code format
 - Makes CPU resources (registers, flags) available to the programmer
 - Allows instructions to access main memory (potentially with limitations)
 - Provides control flow mechanisms (instructions to change what executes next)

What are registers? Do we even need them?

- A. Registers are small and fast memory used as scratch space (to store temporary variables) to perform operations on the ALU
- B. Registers are on the same chip as the ALU.
- C. We can move data and instructions from main memory to registers, through a bus (group of wires) connecting main memory to the register file.
- D. General purpose registers are accessed via %rax %ebp. Special purpose registers like the program counter reference the location of the next instruction in main memory.
- E. All of the above



Processor State in Registers

Working memory for currently executing program

- Temporary data: %rax %r15
- Current stack frame
- %rbp: base pointer
- %rsp: stack pointer
- Address of next instruction to execute: %rip
- Status of recent ALU tests
 (CF, ZF, SF, OF)



Component Registers

- Registers starting with "r" are 64-bit registers
 - %rax, %rbx, ..., %rsi, %rdi
- Sometimes, you might only want to store 32 bits (e.g., int variable)
 - You can access the lower 32 bits of a register with prefix e:
 - %eax, %ebx, ..., %esi, %edi
 - with a suffix of d for registers %r8 to %r15
 - %r8d, %r9d, ..., %r15d



Assembly Programmer's View of State



Registers:

PC: Program counter (%rip)Condition codes (%RFLAGS)General Purpose (%rax - %r15)

Memory:

- Byte addressable array
- Program code and data
- Execution stack

Types of assembly instructions

- Data movement
 - Move values between registers and memory
 - Examples: mov, movl, movq
- Load: move data from memory to register
- Store: move data from register to memory

The suffix letters specify how many bytes to move (not always necessary, depending on context).

> l -> 32 bits q -> 64 bits

Data Movement

Move values between memory and registers or between two registers.



Types of assembly instructions

• Data movement

Move values between registers and memory

- Arithmetic
 - Uses ALU to compute a value
 - Examples: add, addl, addq, sub, subl, subq...

Arithmetic

Use ALU to compute a value, store result in register / memory.


Types of assembly instructions

• Data movement

Move values between registers and memory

- Arithmetic
 - Uses ALU to compute a value
- Control
 - Change PC based on ALU condition code state
 - Example: jmp

Control

Change PC based on ALU condition code state.



Types of assembly instructions

- Data movement
 - Move values between registers and memory
- Arithmetic
 - Uses ALU to compute a value
- Control
 - Change PC based on ALU condition code state
- Stack / Function call (We'll cover these in detail later)
 Shortcut instructions for common operations

Addressing Modes

- Instructions need to be told where to get operands or store results
- Variety of options for how to *address* those locations
- A location might be:
 - A register
 - A location in memory
- In x86_64, an instruction can access <u>at most one</u> memory location

Addressing Modes

- Instructions can refer to:
 - the name of a register (%rax, %rbx, etc)
 - to a constant or "literal" value, starts with \$
 - (%rax) : accessing memory
 - treat the value in %rax as a memory address,

Addressing Mode: Memory

movl (%rcx), %rax

- Use the address in register %rcx to access memory,
- then, store result at that memory address in register %rax



Addressing Mode: Memory

movl (%rcx), %rax

- Use the address in register %rcx to access memory,
- then, store result at that memory address in register %rax



Addressing Mode: Register

- Instructions can refer to the name of a register
- Examples:
 - mov %rax, %r15
 (Copy the contents of %rax into %r15 -- overwrites %r15, no change to %rax)
 - add %r9, %rdx

(Add the contents of %r9 and %rdx, store the result in %rdx, no change to %r9)

Addressing Mode: Immediate

- Refers to a constant or "literal" value, starts with \$
- Allows programmer to hard-code a number
- Can be either decimal (no prefix) or hexadecimal (0x prefix)

mov **\$10**, %rax

– Put the constant value 10 in register rax.

add \$0xF, %rdx

- Add 15 (0xF) to %rdx and store the result in %rdx.

Addressing Mode: Memory

- Accessing memory requires you to specify which address you want.
 - Put the address in a register.
 - Access the register with () around the register's name.

mov (%rcx), %rax

 Use the address in register %rcx to access memory, store result in register %rax

Addressing Mode: Displacement

- Like memory mode, but with a constant offset
 - Offset is often negative, relative to %rbp
- movl -16(%rbp), %rax
 - Take the address in %rbp, subtract 16 from it, index into memory and store the result in %rax.

Addressing Mode: Displacement

movl -16(%rbp), %rax

 Take the address in %rbp, subtract 16 from it, index into memory and store the result in %rax.



Addressing Mode: Displacement

movl -16(%rbp), %rax

 Take the address in %rbp, subtract 24 from it, index into memory and store the result in %rax.



Let's try a few examples...

What will the state of registers and memory look like after executing these instructions?

- sub \$16, %rsp
 movq \$3, -8(%rbp)
- mov **\$10,** %rax
- sal **\$1,** %rax
- add -8(%rbp), %rax
 movq %rax, -16(%rbp)
- add \$16, %rsp

Memory Registers **Address** Value Value Name ... 0 0x1FFF000AD0 %rax 0 0x1FFF000AE0 %rsp 0×1FFF000AD8 0 %rbp 0x1FFF000AE0-0x1FFF000AE0 0x1FFF000AF0 ...

What will the state of registers and memory look like after executing these instructions?

sub \$16, %rsp
movq \$3, -8(%rbp)
mov \$10, %rax
sal \$1, %rax
add -8(%rbp), %rax
movq %rax, -16(%rbp)
add \$16, %rsp

		<u>Registers</u>		Mem	ory
	Name	Value		Address	Value
	%rax	2]	0x1FFF000AD0	3
Α.	%rsp	0x1FFF000AE0]	0x1FFF000AD8	10
	%rbp	0x1FFF000AE0	┝──►	0x1FFF000AE0	0x1FFF000AF0
			-	Г	
	<u>Registers</u>			Memory	
	Name	Value		Address	Value
	%rax	10		0x1FFF000AD0	23
Β.	%rsp	0x1FFF000AE0]	0x1FFF000AD8	10
	%rbp	0x1FFF000AE0	┝──►	0x1FFF000AE0	0x1FFF000AF0
			-		
	Registers			Mem	ory
	Name	Value		Address	Value
C.	%rax	23]	0x1FFF000AD0	23
	%rsp	0x1FFF000AE0]	0x1FFF000AD8	3
	%rbp	0x1FFF000AE0	┝──	0x1FFF000AE0	0x1FFF000AF0

Solution

sub \$16, %rsp
movq \$3, -8(%rbp)
mov \$10, %rax
sal \$1, %rax
add -8(%rbp), %rax
movq %rax, -16(%rbp)
add \$16, %rsp

<u>Registers</u>			Memory	
Name	Value		Address	Value
%rax	0		0x1FFF000AD0	0
%rsp	AE0		0x1FFF000AD8	0
%rbp	AE0	├ →	0x1FFF000AE0	0x1FFF000AF0

Assembly Visualization Tool

- The authors of Dive into Systems, including Swarthmore faculty with help from Swarthmore students, have developed a tool to help visualize assembly code execution:
- <u>https://asm.diveintosystems.org</u>
- For this example, use the arithmetic mode.

sub	\$16, %rsp
movq	\$3, -8(%rbp)
mov	\$10, %rax
sal	\$1, %rax
add	-8 <mark>(%rbp),</mark> %rax
movq	%rax, -16(%rbp)
add	\$16, %rsp

Solution

sub \$16, %rsp
movq \$3, -8(%rbp)
mov \$10, %rax
sal \$1, %rax
add -8(%rbp), %rax
movq %rax, -16(%rbp)
add \$16, %rsp

Subtract constant 16 from %rsp Move constant 3 to address %rbp-8 Move constant 10 to register %rax Shift the value in %rax left by 1 bit Add the value at address %rbp-8 to %rax Store the value in %rax at address rbp-16 Add constant 16 to %rsp

<u>Registers</u>		Memory	
Name	Value	Address	Value
%rax	23	0x1FFF000AD0	23
%rsp	AE0	0x1FFF000AD8	3
%rbp	AE0	 0x1FFF000AE0	0x1FFF000AF0

What will the state of registers and memory look like after executing these instructions?

mov %rbp, %rcx
sub \$8, %rcx
movq (%rcx), %rax
or %rax, -16(%rbp)
neg %rax

...

<u>Registers</u>			Memory	
Name	Value		Address	Value
%rax	0			
%rcx	0		0x1FFF000AD0	8
%rsp	0x1FFF000AE0		0x1FFF000AD8	5
%rbp	0x1FFF000AE0-		0x1FFF000AE0	0x1FFF000AF0
		•		

How might you implement the following C code in assembly? $z = x \wedge y$

x is stored at %rbp-8 y is stored at %rbp-16 z is stored at %rbp-24

```
A: movq -8(%rbp), %rax
movq -16(%rbp), %rdx
xor %rax, %rdx
movq %rax, -24(%rbp)
```

```
movq -8(%rbp), %rax
B: movq -16(%rbp), %rdx
xor %rdx, %rax
movq %rax, -24(%rbp)
```

	<u>Registers</u>	Memory		
Name	Value	Address	Value	
%rax	0	0x1FFF000AC8	(z)	
%rdx	0	0x1FFF000AD0	(у)	
%rsp	0x1FFF000AE0	0x1FFF000AD8	(x)	
%rbp	0x1FFF000AE0	Ox1FFF000AE0	0x1FFF000AF0	
movq movq xor movq	-8 <mark>(%rbp),</mark> %rax -16 <mark>(%rbp),</mark> %rdx %rax, %rdx %rax, -8 <mark>(%rbp)</mark>			
movq	-24 <mark>(%rbp),</mark> %rax			

movq -24(%rbp), %rax
D:
movq -16(%rbp), %rax
xor %rdx, %rax
movq %rax, -8(%rbp)

How might you implement the following C code in assembly? x = y >> 3 | x * 8

x is stored at %rbp-8y is stored at %rbp-16z is stored at %rbp-24

Registers		Memory	
Name	Value	Address	Value
%rax	0	0x1FFF000AC8	(z)
%rdx	0	0x1FFF000AD0	(y)
%rsp	0x1FFF000AE0	0x1FFF000AD8	(x)
%rbp	0x1FFF000AE0-	 0x1FFF000AE0	0x1FFF000AF0
	4		

Solutions (other instruction sequences can work too!)

• z = x ^ y

movq -8(%rbp), %rax
movq -16(%rbp), %rdx
xor %rdx, %rax
movq %rax, -24(%rbp)

mov -8(%rbp), %rax imul \$8, %rax movq -16(%rbp), %rdx sar \$3, %rdx or %rax, %rdx movq %rdx, -8(%rbp)

Recall Memory Operands

- displacement(%reg)
 -e.g., add %rax, -8(%rbp)
- x86_64 allows a memory operand as the source or destination, but NOT BOTH!
 - One of the operands must be a register
- This would <u>not</u> be allowed:
 - -add -8(%rbp), -16(%rbp)
 - If you wanted this, movq one value into a register first

Control Flow

- Previous examples focused on:
 - data movement (mov, movq)
 - arithmetic (add, sub, or, neg, sal, etc.)
- Up next: Jumping!

(Changing which instruction we execute next.)



Relevant XKCD





<u>xkcd #292</u>

Unconditional Jumping / Goto

A label is a place you <u>might</u> jump to.

Labels ignored except for goto/jumps.

(Skipped over if encountered)

goto label1; a = a + b; label1: return;

int main(void) {

long a = 10;

long b = 20;

int x = 20; L1: int y = x + 30; L2: printf("%d, %d\n", x, y);

Unconditional Jumping / Goto

```
int main(void) {
```

```
long a = 10;
long b = 20;
```

```
goto label1;
a = a + b;
```

label1:

return;

pushq %rbp mov %rsp, %rbp sub **\$16**, %rsp movq \$10, -16(%ebp) movq \$20, -8(%ebp) jmp label1 movq -8(%rbp), \$rax these instructions add \$rax, -16(%rbp) are never executed in this movq -16(%rbp), %rax code label1: leave

Unconditional Jumping / Goto

Usage besides goto?

- infinite loop
- break;
- continue;
- functions (handled differently)
- Often, we only want to jump when *some condition* is true / false.
- We need some way to compare values, jump based on comparison results.

pushq %rbp mov %rsp, %rbp sub **\$16**, %rsp movq \$10, -16(%ebp) movq \$20, -8(%ebp) jmp label1 movq -8(%rbp), \$rax add \$rax, -16(%rbp) movq -16(%rbp), %rax label1: leave

Condition Codes (or Flags)

- Set in two ways:
 - 1. As "side effects" produced by ALU
 - 2. In response to explicit comparison instructions
- x86_64 condition codes tell you:
 - If the result is zero (ZF)
 - If the result's first bit is set (negative if signed) (SF)
 - If the result overflowed (assuming unsigned) (CF)
 - If the result overflowed (assuming signed) (OF)

Processor State in Registers

Working memory for currently executing program

- Temporary data: %rax %r15
- Current stack frame
- %rbp: base pointer
- %rsp: stack pointer
- Address of next instruction to execute: %rip
- Status of recent ALU tests
 (CF, ZF, SF, OF)



Instructions that set condition codes

- 1. Arithmetic/logic side effects (add, sub, or, etc.)
- 2. CMP and TEST:
 - **cmp b**, **a** like computing **a**-**b** without storing result
 - Sets OF if overflow, Sets CF if carry-out, Sets ZF if result zero, Sets SF if results is negative

test b, a like computing a & b without storing result

Sets ZF if result zero, sets SF if a&b < 0
 OF and CF flags are zero (there is no overflow with &)

Which flags would this sub set?

Suppose %rax holds 5, %rcx holds 7

Sub \$5, %raxIf the result is zero (ZF)If the result's first bit is set (negative if signed) (SF)If the result overflowed (assuming unsigned) (CF)If the result overflowed (assuming signed) (OF)

Which flags would this sub set?

Suppose %rax holds 5, %rcx holds 7

Sub \$5, %raxIf the result is zero (ZF)If the result's first bit is set (negative if signed) (SF)If the result overflowed (assuming unsigned) (CF)If the result overflowed (assuming signed) (OF)

Which flags would this cmp set?

Suppose %rax holds 5, %rcx holds 7

cmp %rcx, %rax

If the result is zero (ZF) If the result's first bit is set (negative if signed) (SF) If the result overflowed (assuming unsigned) (CF) If the result overflowed (assuming signed) (OF)

Which flags would this cmp set?

Suppose %rax holds 5, %rcx holds 7

cmp %rcx, %rax

If the result is zero (ZF) If the result's first bit is set (negative if signed) (SF) If the result overflowed (assuming unsigned) (CF) If the result overflowed (assuming signed) (OF)
Conditional Jumping

Jump based on which condition codes are set

Jump Instructions: (See book section 7.4.1)

You do not need to memorize these!

	Condition	Description
jmp	1	Unconditional
je	ZF	Equal / Zero
jne	~ZF	Not Equal / Not Zero
js	SF	Negative
jns	~SF	Nonnegative
jg	~ (SF^OF) &~ZF	Greater (Signed)
jge	~ (SF^OF)	Greater or Equal (Signed)
jl	(SF^OF)	Less (Signed)
jle	(SF^OF) ZF	Less or Equal (Signed)
ja	~CF&~ZF	Above (unsigned jg)
jb	CF	Below (unsigned)

Example Scenario

```
long userval;
scanf("%ld", &userval);
```

```
if (userval == 42) {
   userval = userval + 5;
} else {
   userval = userval - 10;
}
```

- Suppose user gives us a value via scanf
- We want to check to see if it equals 42
 - If so, add 5
 - If not, subtract 10

How would we use jumps/CCs for this?

```
long userval;
scanf("%ld", &userval);
```

Assume userval is stored in %rax at this point.

```
if (userval == 42) {
   userval = userval + 5;
} else {
   userval = userval - 10;
}
```

How could we use jumps/CCs to implement this C code?



How could we use jumps/CCs to implement this C code?



```
(C) cmp $42, %rax
    jne L2
L1:
    add $5, %rax
    jmp DONE
L2:
    sub $10, %rax
DONE:
```

Visualization demo

Try this in arithmetic mode:

https://asm.diveintosystems.org

Change the value 3 to 42 to alter the behavior.

```
# Initialize rax
mov $3, %rax
```

```
cmp $42, %rax
je L2
L1:
  sub $10, %rax
  jmp DONE
L2:
  add $5, %rax
DONE:
```

C Loops to x86_64

<pre>do-while: do { loop body } while (cond);</pre>	<u>Cgoto translations:</u> loop: loop body if(cond) goto loop
<pre>while: while(cond) { loop body }</pre>	<pre>if(!cond) goto done loop: loop body if(cond) goto loop done:</pre>
<pre>for: for(init; cond; step){ loop body }</pre>	<pre>init code if(!cond) goto done loop: loop body step if(cond) goto loop done:</pre>

Convert to C goto:

for:	init code
	<fill answer="" here="" in="" your=""></fill>
<pre>for(init; cond; step){ loop body </pre>	
ן נססף boay ג	

Convert to C goto:

<pre>for: for(init; cond; step){ loop body</pre>	<pre>init code if(!cond) goto done loop: loop body</pre>
}	<pre>step if(cond) goto loop done:</pre>

Using Jump Instructions

- jmp label #unconditionaljump (ex. jmp .L2)
- jge label # conditional jump (ex. if >=) (je, jne, js, jg, ...)

(A label is a place you <u>might</u> jump to. Labels ignored except for goto/jumps)

Try out this code: what does it do?

```
movl $0, %rax
movl $4, %rbx
movl $0, %rdx
jmp .L2
.L1:
  addl $1, %rax
.L2:
  addl %rax, %rdx
  cmp %rax, %rbx # R[%ebx] - R[%eax]
  jge .L1
```

CPU Registers		
	%rax	
	%rdx	
	%rbx	

Using Jump Instructions

- jmp label #unconditionaljump (ex. jmp .L2)
- jge label # conditional jump (ex. if >=) (je, jne, js, jg, ...)

(A label is a place you <u>might</u> jump to. Labels ignored except for goto/jumps)

Try out this code: what does it do?

```
movq $0, %rax
movq $4, %rbx
movq $0, %rdx
jmp .L2
.L1:
addq $1, %rax
.L2:
addq %rax, %rdx
cmp %rax, %rbx # R[%rbx] - R[%rax]
jge .L1
```

CPU Registers		
§rax	0 1	
%rdx	0	
%rbx	4	

Loops

• We will look at more of these in the lab!

Summary

- ISA defines what programmer can do on hardware
 - Which instructions are available
 - How to access state (registers, memory, etc.)
 - This is the architecture's assembly language
- In this course, we'll be using x86_64
 - Instructions for:
 - moving data (mov, movl, movq)
 - arithmetic (add, sub, imul, or, sal, etc.)
 - control (jmp, je, jne, etc.)
 - Condition codes for making control decisions
 - If the result is zero (ZF)
 - If the result's first bit is set (negative if signed) (SF)
 - If the result overflowed (assuming unsigned) (CF)
 - If the result overflowed (assuming signed) (OF)